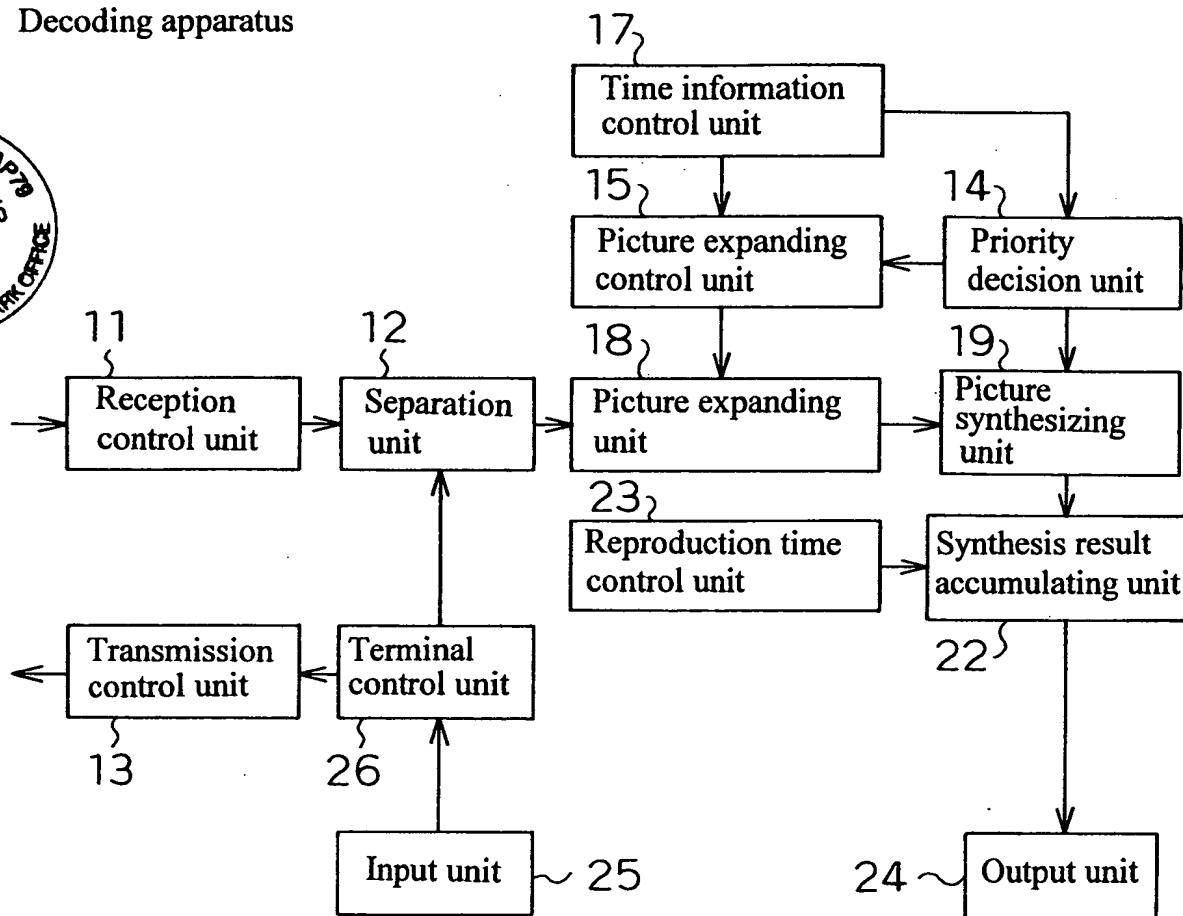


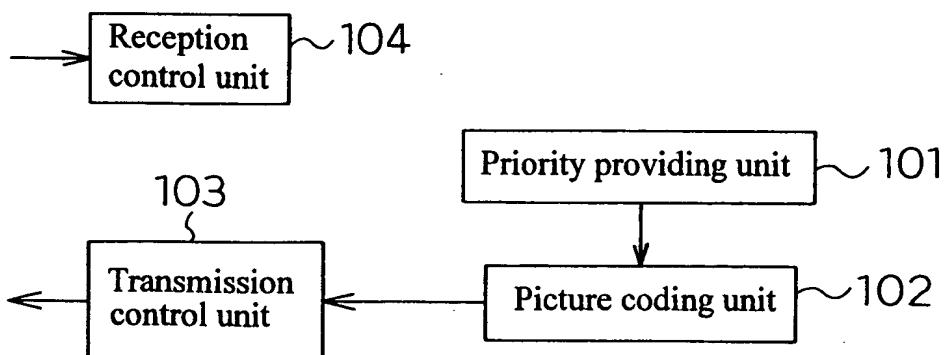
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Fig. 1

Decoding apparatus

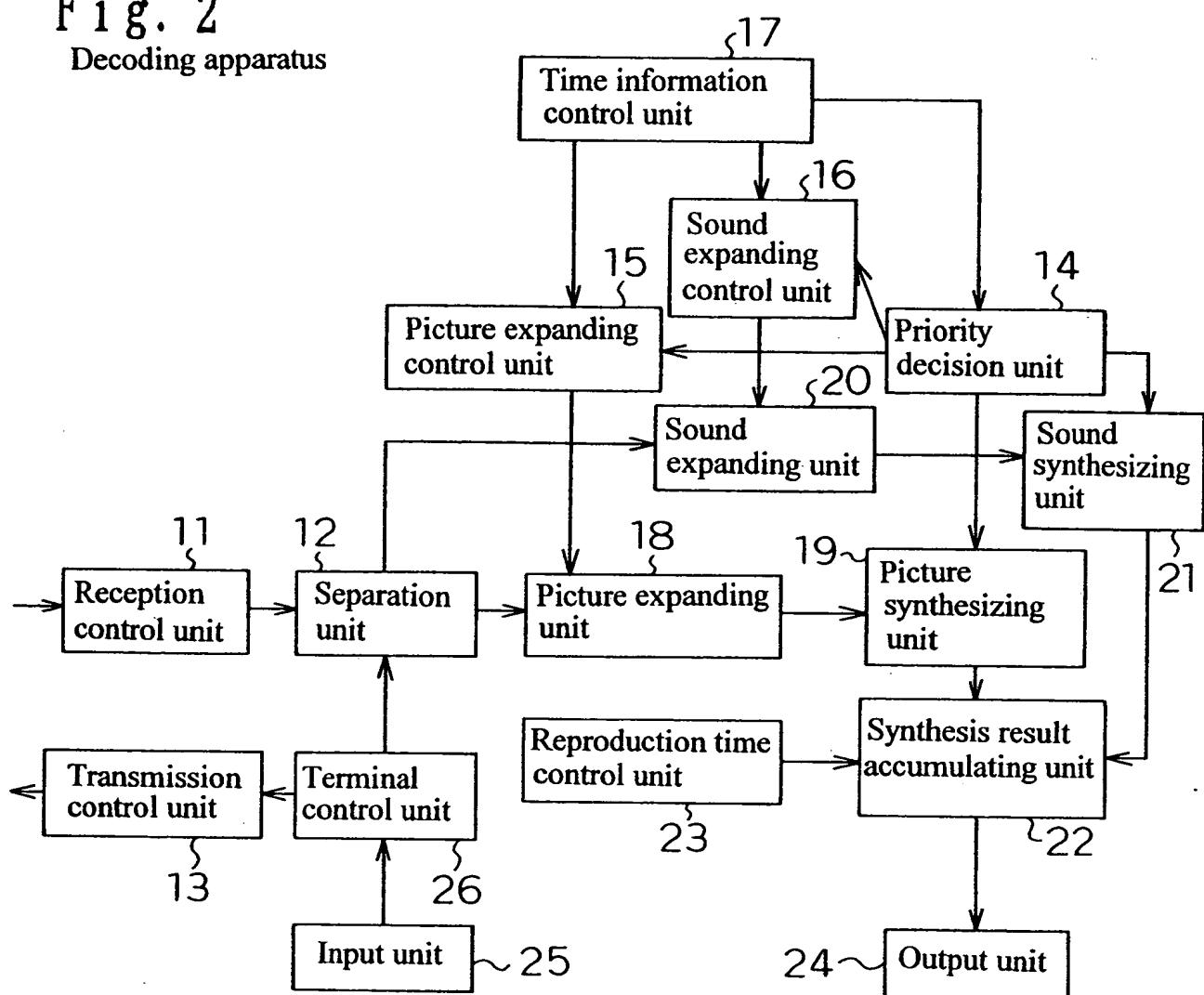


Coding apparatus



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Fig. 2
Decoding apparatus



Coding apparatus

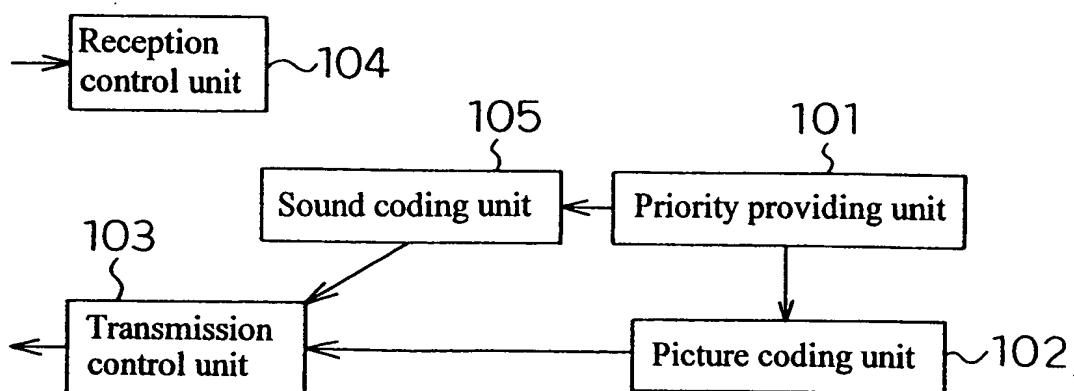


Fig. 3 (a)

All multiplexed format

Header information	Priority for defining reproduction sequence	Priority for defining processing when overloaded	Picture data 1	Sound data 1	Picture data N	Sound data N
--------------------	---	--	----------------	--------------	-------	----------------	--------------

Information showing display sequence
 ↓

* The information describing the relation between pictures or between sounds may be described in the header information.

Fig. 3 (b)

Multiplexed in individual media, and transmitted from respective communication ports

Header information	Priority for defining reproduction sequence	Priority for defining processing when overloaded
--------------------	---	--

Header information	Picture data 1	Picture data N
--------------------	----------------	-------	----------------

Picture data row

Header information	Sound data 1	Sound data N
--------------------	--------------	-------	--------------

Sound data row

Fig. 4

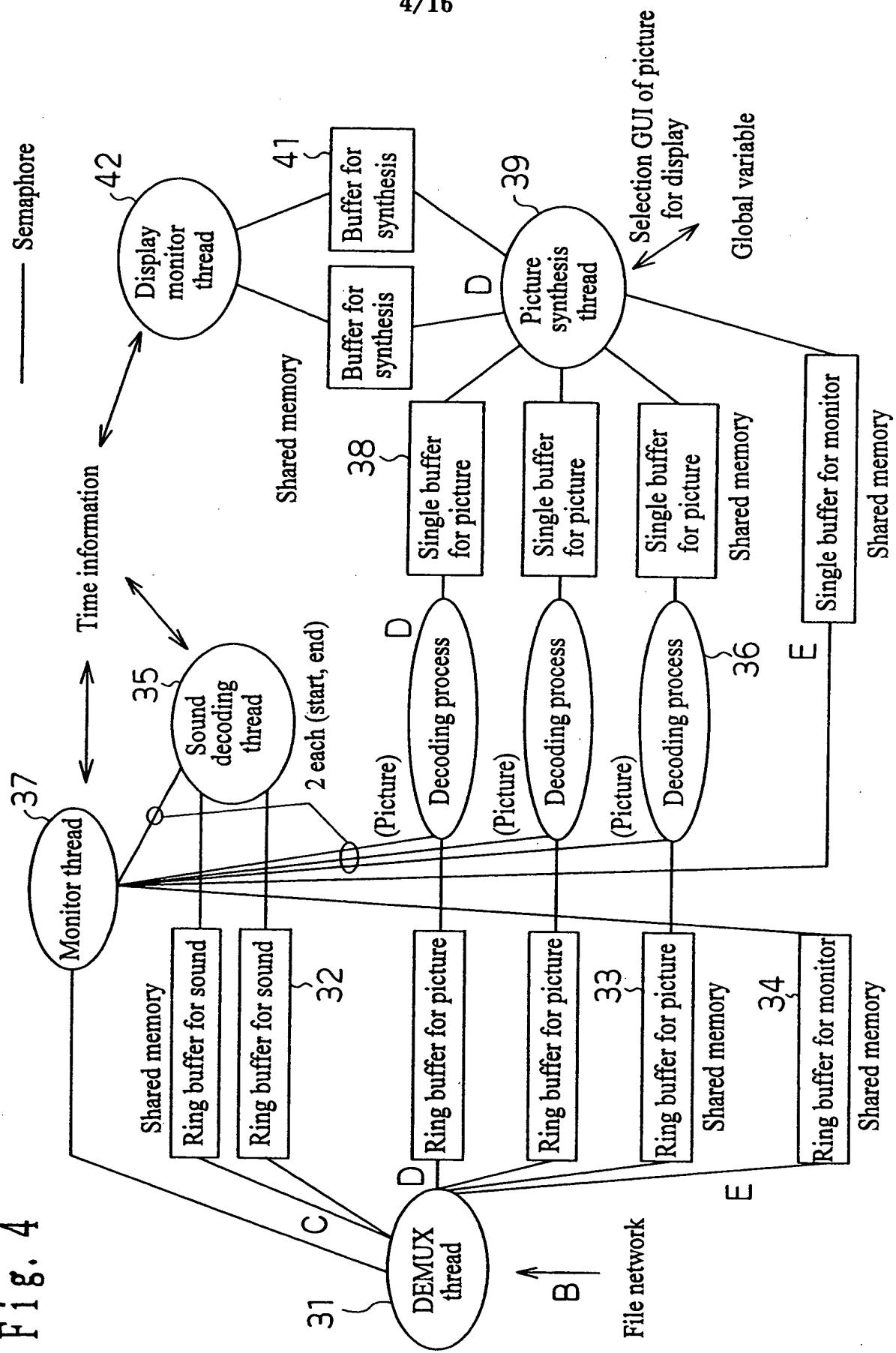


Fig. 5

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B.

```
struct shm_tspkt {
    data_byte      188byte      Packet data
}
```

C.

```
struct shm_apkt {
    DWORD sync_code      32bit  Packet synchronous code
    WORD  pts            16bit  Display time
    WORD  frame_length  16bit  Frame length
    BYTE  data_byte      Nbyte  Sound data
                                (N=frame_length)
}
```

D.

```
struct shm_vpkt {
    DWORD sync_code      32bit  Packet synchronous code
    BYTE  temporal_reference 8bit  Frame number
    WORD  frame_length    16bit  Frame length
    BYTE  data_byte      Nbyte  Picture data
                                (N=frame_length)
}
```

E.

```
struct shm_kanshi_lInfo {
    WORD  pts            16bit  Display time
    BYTE  number_of_object  8bit  No. of objects
    for (i=0: i<number_of_object:i++)  {
        BYTE  object_id      8bit  ID
        BYTE  temporal_reference 8bit  Frame number
        BYTE  object_priority  4bit  Priority (*1)
        reserved            2bit
        IPB_flag            2bit  Frame type
        WORD  horizontal_offset 10bit  Display position, horizontal
        WORD  vertical_offset  10bit  Display position, vertical
        BYTE  layer           4bit  Layer
    }
}
```

(*1) Bits are assigned from the highest position sequentially by 4 bits
(object_priority), 2 bits, 2 bits (IPB_flag)

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Fig. 6

DEMUX thread

```
void demux ( )
{
    Shared memory (ring), semaphore generation process: for output
        (2 for sound, 3 for picture, 1 for monitor table)
    Semaphore generation for monitor thread control (one)
    BOOL flag = TRUE: // State of ring buffer

    while(1) {
        if (flag) Reading from file or network - (5-1)

        if (flag)
            Analysis of 188-byte packet data, setting in specified structure - (5-2)
            (decomposed into information of sound, picture, monitor table)

            // Exclusive control of ring buffer by semaphore
            if (Able to write in ring buffer ?){
                Write into ring buffer (from earlier object ID, write sequentially - (5-3)
                    into shared memory of earlier buffer number)
                Advance write pointer of written buffer - (5-4)
                flag=TRUE:
            }else
                flag=FALSE: // Prevent overflow of ring buffer

        if (flag)
            After writing information of pictures and sounds for one monitor - (5-5)
            table, advance the counter of semaphore for monitor thread control
    }
}
```

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Fig. 7

Monitor thread

```
void Watch Process ( )
{
    BYTE disp_TR[i]: // Picture serial number (shared memory)
    BOOL skip_flag[i]: // Skip flag to which decoding process refers
                        (shared memory)

    Shared memory (ring buffer: monitor table 1)
        Semaphore open: used by determining priority of processing
    Shared memory (single buffer: monitor table 1)
        Semaphore generation: transfer to synthesis side
    Generation of semaphore for process monitor
    Semaphore open for monitor thread control (one)

    Start of picture decoding process
    Confirm start of process
    while {skip_flag[i]=FALSE: // Not skipped }

    while(1)
    {
        Reading of monitor table (read pointer update, from DEMUX)
        Check of object priority - (6-1) - (6-2)
        Writing of monitor table (to synthesis side) - (6-3)
        Wait for creation of data for one monitor table from DEMUX - (6-4)

        From highest priority
        {
            disp_TR[i]=TR:
            if ( Present time > display time (pts) ) {
                Not skipped if I frame
                skip_flag[i]=FALSE
            }else{
                P, B frames are skipped
                skip_flag[i]=TRUE
            }
            Release of semaphore of corresponding process - (6-7)
            Wait for release of semaphore of corresponding process
                (process completion check) - (6-8)
        }
    }
}
```

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Fig. 8

Decoding process

```
void main(int argc, char *argv[ ] )  
{
```

Value received from main process :

Shared memory to be opened, name of semaphore

Shared memory (ring), open processing of semaphore: for input (from MUX)

Shared memory (single), open processing of semaphore: for output (to synthesis
side)

```
while(1) {
```

 Monitor thread waits for release of semaphore - (7-1)

 Input picture state check: - (7-2)

 Picture serial number (TR), skip input frame?

 Wait for picture data to be decoded - (7-3)

 Is TR present in shared memory? { - (7-4)

 Skip decoding if not present

 Advance read pointer for ring buffer (for input)

}

 if (Skip one input frame) {

 Decoding process - (7-5)

 Advance read pointer for ring buffer (for input)

}

 Output of decoding result (*1) - (7-6)

 Release semaphore to monitor thread (process end notice) - (7-7)

}

(*1) When skipping input frame process, send signal to main process without
decoding process and output of decoding result

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Fig. 9

Picture synthesis thread

```
void Watch Sync ( )
{
    Shared memory (single), semaphore generation process: for input (from decoder)
    Shared memory (single), semaphore generation process: for input (from monitor
                                                thread)
    Shared memory (single), semaphore generation process: for output (to display
                                                monitor: 2)
    BOOL flag=TRUE:

    while(1)  {
        Wait for monitor table from monitor thread          - (8-1)
        Check priority order of object                      - (8-2)

        From highest priority order  {                      - (8-3)
            Wait for picture of decoding result (accumulated in shared memory)
            //  Totally black if empty
        }

        Synthesis of image adjusting to display position      - (8-4)

        //  Double buffer
        if (flag)  {                                      - (8-5)
            Write synthesis result into shared memory (to display monitor) #1
            flag=FALSE:
        } else {
            Write synthesis result into shared memory (to display monitor) #2
            flag=TRUE:
        }
    }
}
```

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Fig. 10

Display monitor thread

```
void Watch Disp ( )
{
    Shared memory (single), open processing of semaphore: for input
    (from synthesis thread: 2)
    BOOL flag = TRUE:

    while(1)
    {
        // Double buffer
        if (flag)  {
            Wait for synthesis picture from shared memory (from synthesis thread)#1
            flag = FALSE:                                - (9-1)
        } else {
            Wait for synthesis picture from shared memory (from synthesis thread)#2
            flag = TRUE:
        }

        if (Initial display)  {
            Acquire display start time from timer          - (9-2)
        }
        Sleep (pts-nowtime):                            - (9-3)
        Display of synthesis picture
    }
}
```

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Fig. 11

Three-dimensional picture
(foreground: helicopter)

Three-dimensional picture
(foreground: balloon)

Background picture
(night sky)

Foreground picture
(building)
Synthesis ratio: 0.5



Foreground picture (man)

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Fig. 12 (a)

System of hardware base

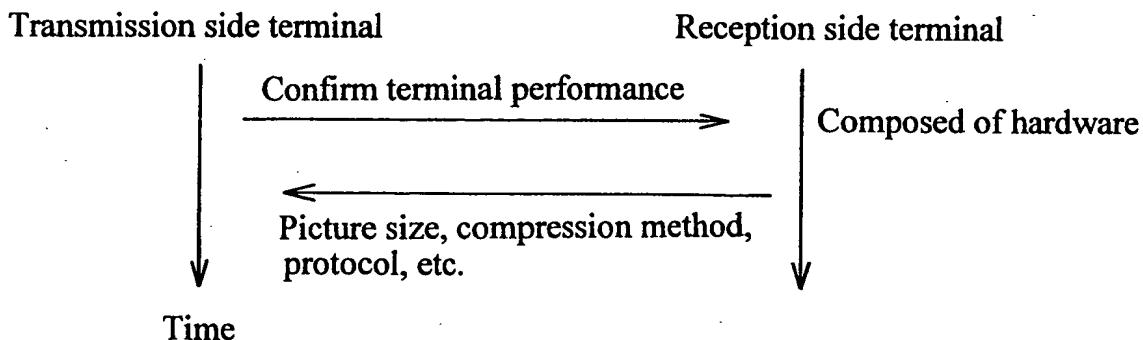
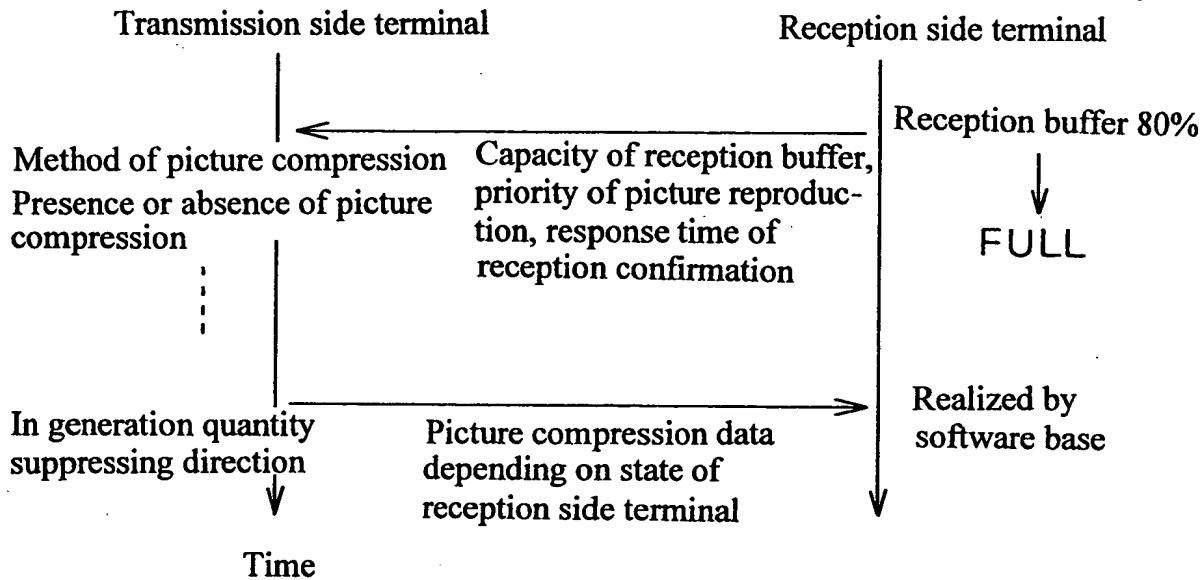


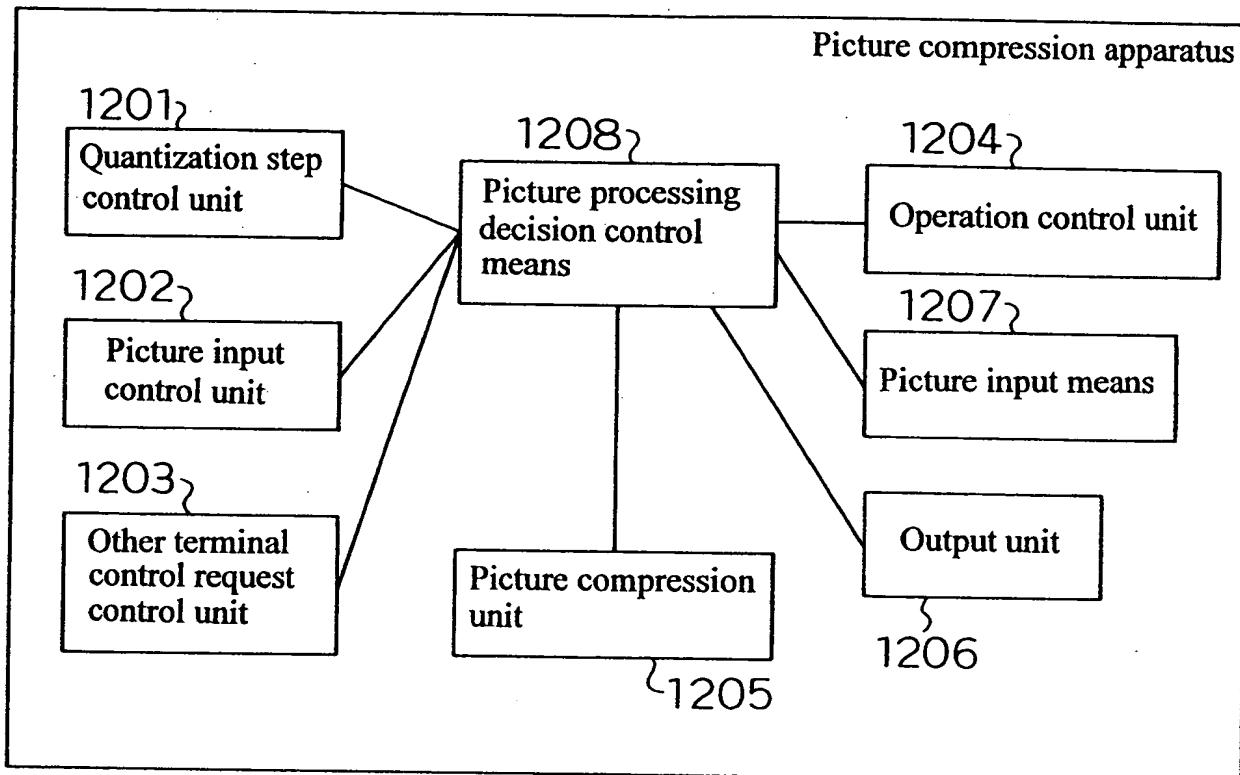
Fig. 12 (b)

System of software base



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Fig. 13



* Sound compression apparatus can be set similarly

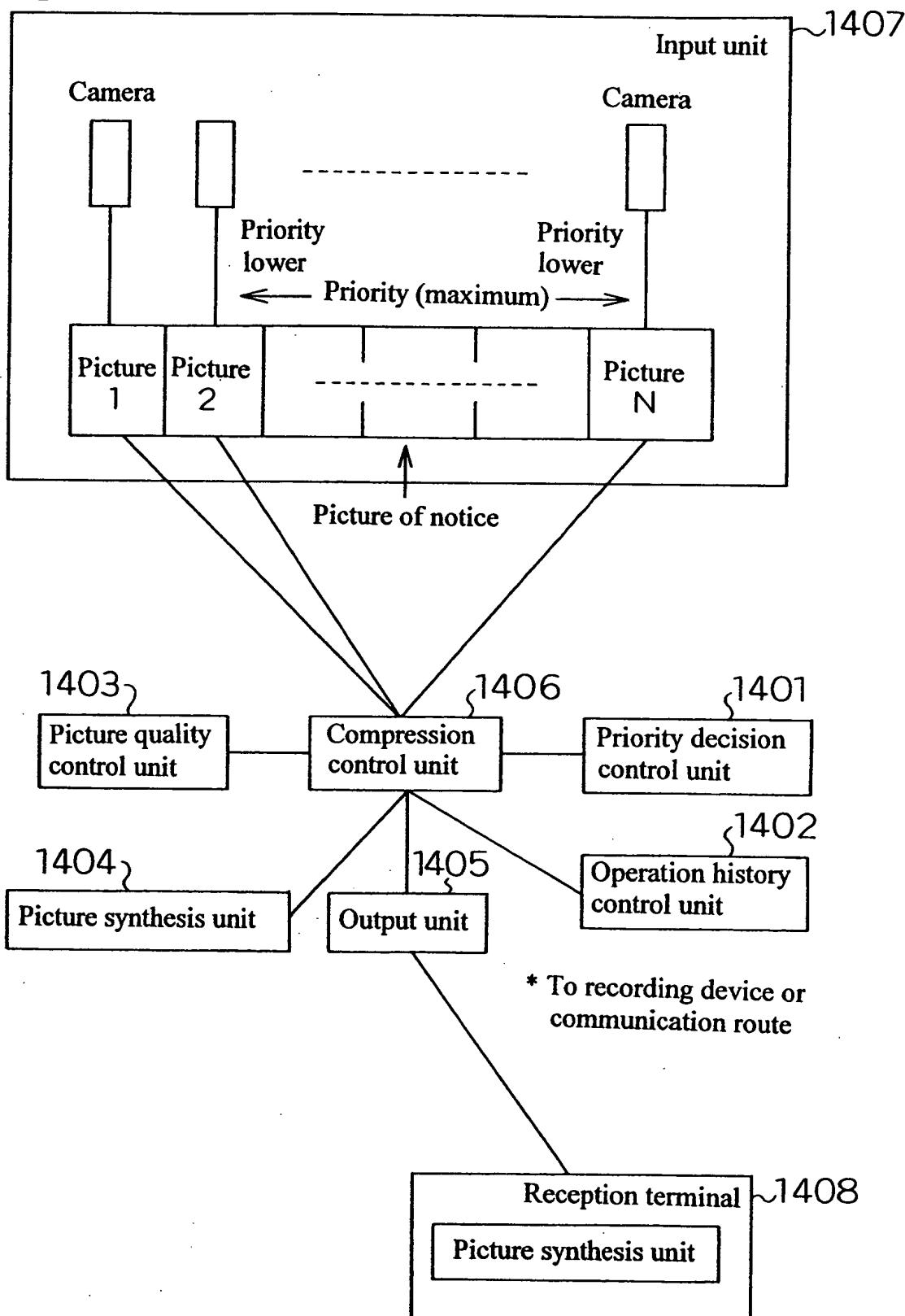
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Fig. 14

Picture size	Camera control	Other terminal control request	Quantization step
QCIF	Pan	Buffer over	16
CIF	None	None	16
QCIF	None	None	18
QCIF	Tilt	None	14

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Fig. 15



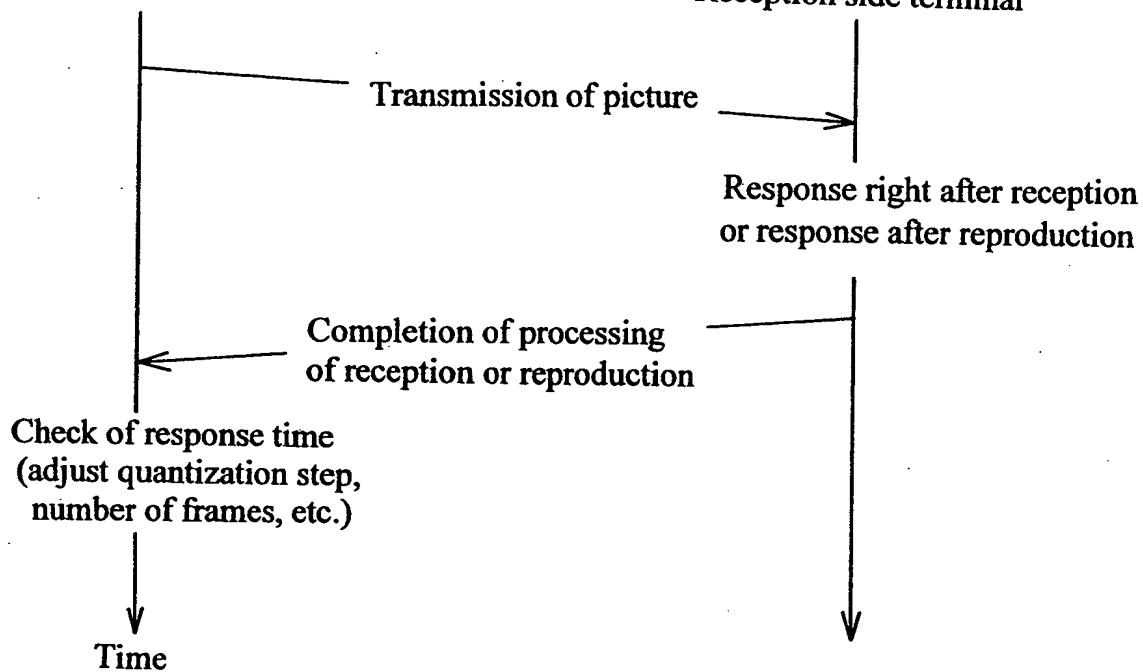
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Fig. 16

○ Feedback relating to response between transmission terminal and reception terminal (case 1)

Transmission side terminal

Reception side terminal



○ Feedback of reproduction situation to transmission side terminal (case 2)

Transmission side terminal

Reception side terminal

